

An Old and a New Source of Endogeneous Fluctuations

Marji Lines

University of Udine
Department of Statistics

Seminar - Baruch College
The City University of New York
23 September 2009

SAMUELSON'S ORIGINAL MODEL - 1939

- consumption - Keynesian multiplier relating C to national income Y

$$C_t = bY_{t-1} \quad 0 < b < 1$$

- investment - autonomous and induced through accelerator

$$I_t = I_a + k(C_t - C_{t-1}) \quad k > 0.$$

- equilibrium in goods market

$$Y_t = C_t + I_t$$

- giving second-order linear difference equation in Y

$$Y_t = I_a + b(1 + k)Y_{t-1} - bkY_{t-2}.$$

SAMUELSON'S ORIGINAL MODEL - 1939

- consumption - Keynesian multiplier relating C to national income Y

$$C_t = bY_{t-1} \quad 0 < b < 1$$

- investment - autonomous and induced through accelerator

$$I_t = I_a + k(C_t - C_{t-1}) \quad k > 0.$$

- equilibrium in goods market

$$Y_t = C_t + I_t$$

- giving second-order linear difference equation in Y

$$Y_t = I_a + b(1 + k)Y_{t-1} - bkY_{t-2}.$$

SAMUELSON'S ORIGINAL MODEL - 1939

- consumption - Keynesian multiplier relating C to national income Y

$$C_t = bY_{t-1} \quad 0 < b < 1$$

- investment - autonomous and induced through accelerator

$$I_t = I_a + k(C_t - C_{t-1}) \quad k > 0.$$

- equilibrium in goods market

$$Y_t = C_t + I_t$$

- giving second-order linear difference equation in Y

$$Y_t = I_a + b(1 + k)Y_{t-1} - bkY_{t-2}.$$

SAMUELSON'S ORIGINAL MODEL - 1939

- consumption - Keynesian multiplier relating C to national income Y

$$C_t = bY_{t-1} \quad 0 < b < 1$$

- investment - autonomous and induced through accelerator

$$I_t = I_a + k(C_t - C_{t-1}) \quad k > 0.$$

- equilibrium in goods market

$$Y_t = C_t + I_t$$

- giving second-order linear difference equation in Y

$$Y_t = I_a + b(1 + k)Y_{t-1} - bkY_{t-2}.$$

LOCAL/GLOBAL DYNAMICS OF SAMUELSON MODEL

equilibrium $\mathcal{Y} = \frac{1}{1-b} I_a$

stability requires $b < \frac{1}{k}$

oscillations

$b < 4k/(1+k)^2$

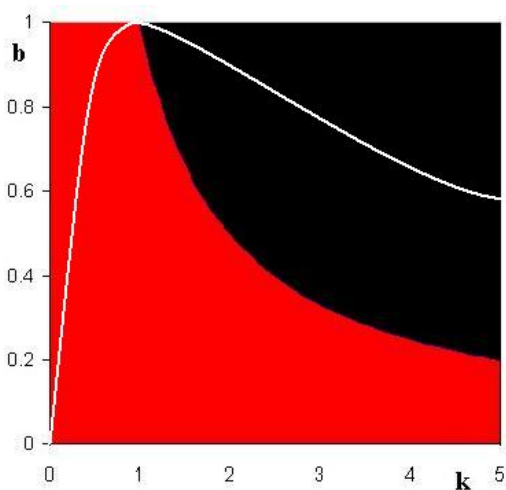
damped oscillations

requires both

persistent cycles at

$b = 1/k$

$b < 4k/(1+k)^2$



PERSISTENT FLUCTUATIONS?

criticism:

- investors and consumers expectations are not modeled
- or national income perceived as martingale - best predictor is last value

possible alternatives:

- representative agent - aggregate expectation is the single homogeneous expectation/agent
- rational expectations - aggregate expectation is average over agents, assumed equal to the future state value
- heterogeneous agents - aggregate expectation is weighted average of agents with fixed expectations
- heterogeneous expectations - aggregate expectation is weighted average of expectations
- many-agents - aggregate expectation (if needed) is average of distribution

PERSISTENT FLUCTUATIONS?

criticism:

- investors and consumers expectations are not modeled
- or national income perceived as martingale - best predictor is last value

possible alternatives:

- representative agent - aggregate expectation is the single homogeneous expectation/agent
- rational expectations - aggregate expectation is average over agents, assumed equal to the future state value
- heterogeneous agents - aggregate expectation is weighted average of agents with fixed expectations
- heterogeneous expectations - aggregate expectation is weighted average of expectations
- many-agents - aggregate expectation (if needed) is average of distribution

HETEROGENEOUS EXPECTATIONS

there is a (small) number of different types of state-dependent expectations circulating in the economy or the market

- for a **given current state** of the economy agents have differing expectations about the future state
- an agent may change type of expectation for **differing states** of the economy

for two types the aggregate expectation for national income at time t , given information set available at time $t - 1$, with proportion of agents w_t using the expectation formation function of the first type, E^1 :

$$E_{t-1}[Y_t] = w_t E_{t-1}^1[Y_t] + (1 - w_t) E_{t-1}^2[Y_t] \quad 0 < w < 1$$

HETEROGENEOUS EXPECTATIONS

there is a (small) number of different types of state-dependent expectations circulating in the economy or the market

- for a **given current state** of the economy agents have differing expectations about the future state
- an agent may change type of expectation for **differing states** of the economy

for two types the aggregate expectation for national income at time t , given information set available at time $t - 1$, with proportion of agents w_t using the expectation formation function of the first type, E^1 :

$$E_{t-1}[Y_t] = w_t E_{t-1}^1[Y_t] + (1 - w_t) E_{t-1}^2[Y_t] \quad 0 < w < 1$$

EXPECTED INCOME

period t income on basis of previous period information: $C_t = bE_{t-1}[Y_t]$

expectations with reference to “long-run” equilibrium - the fixed point of Samuelson's model

- extrapolative expectations (local destabilizing force near normal values)

$$E_{t-1}^1[Y_t] = Y_{t-1} + \mu_1(Y_{t-1} - \mathcal{Y}) \quad \mu_1 > 0.$$

- equilibrium-reverting expectations (global stabilizing force), with adjustment speed μ_2

$$E_{t-1}^2[Y_t] = Y_{t-1} + \mu_2(\mathcal{Y} - Y_{t-1}) \quad 0 < \mu_2 < 1$$

expectations depend on the previous value of national income, but so does the proportion of agents using a given type

EXPECTED INCOME

period t income on basis of previous period information: $C_t = bE_{t-1}[Y_t]$

expectations with reference to “long-run” equilibrium - the fixed point of Samuelson’s model

- extrapolative expectations (local destabilizing force near normal values)

$$E_{t-1}^1[Y_t] = Y_{t-1} + \mu_1(Y_{t-1} - \mathcal{Y}) \quad \mu_1 > 0.$$

- equilibrium-reverting expectations (global stabilizing force), with adjustment speed μ_2

$$E_{t-1}^2[Y_t] = Y_{t-1} + \mu_2(\mathcal{Y} - Y_{t-1}) \quad 0 < \mu_2 < 1$$

expectations depend on the previous value of national income, but so does the proportion of agents using a given type

EXPECTED INCOME

period t income on basis of previous period information: $C_t = bE_{t-1}[Y_t]$

expectations with reference to “long-run” equilibrium - the fixed point of Samuelson’s model

- extrapolative expectations (local destabilizing force near normal values)

$$E_{t-1}^1[Y_t] = Y_{t-1} + \mu_1(Y_{t-1} - \mathcal{Y}) \quad \mu_1 > 0.$$

- equilibrium-reverting expectations (global stabilizing force), with adjustment speed μ_2

$$E_{t-1}^2[Y_t] = Y_{t-1} + \mu_2(\mathcal{Y} - Y_{t-1}) \quad 0 < \mu_2 < 1$$

expectations depend on the previous value of national income, but so does the proportion of agents using a given type

EXPECTED INCOME

period t income on basis of previous period information: $C_t = bE_{t-1}[Y_t]$

expectations with reference to “long-run” equilibrium - the fixed point of Samuelson’s model

- extrapolative expectations (local destabilizing force near normal values)

$$E_{t-1}^1[Y_t] = Y_{t-1} + \mu_1(Y_{t-1} - \mathcal{Y}) \quad \mu_1 > 0.$$

- equilibrium-reverting expectations (global stabilizing force), with adjustment speed μ_2

$$E_{t-1}^2[Y_t] = Y_{t-1} + \mu_2(\mathcal{Y} - Y_{t-1}) \quad 0 < \mu_2 < 1$$

expectations depend on the previous value of national income, but so does the proportion of agents using a given type

EXPECTED INCOME

period t income on basis of previous period information: $C_t = bE_{t-1}[Y_t]$

expectations with reference to “long-run” equilibrium - the fixed point of Samuelson’s model

- extrapolative expectations (local destabilizing force near normal values)

$$E_{t-1}^1[Y_t] = Y_{t-1} + \mu_1(Y_{t-1} - \mathcal{Y}) \quad \mu_1 > 0.$$

- equilibrium-reverting expectations (global stabilizing force), with adjustment speed μ_2

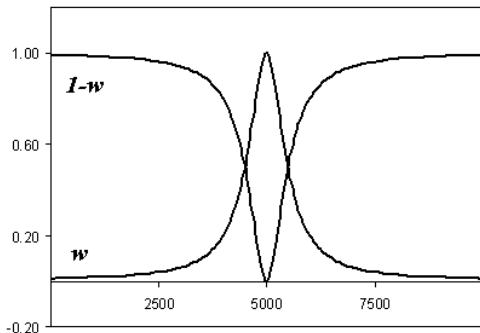
$$E_{t-1}^2[Y_t] = Y_{t-1} + \mu_2(\mathcal{Y} - Y_{t-1}) \quad 0 < \mu_2 < 1$$

expectations depend on the previous value of national income, but so does the proportion of agents using a given type

WEIGHTED EXPECTATIONS

more the economy deviates from \mathcal{Y} , less weight given to extrapolative expectations

agents believe that extreme economic conditions are not sustainable



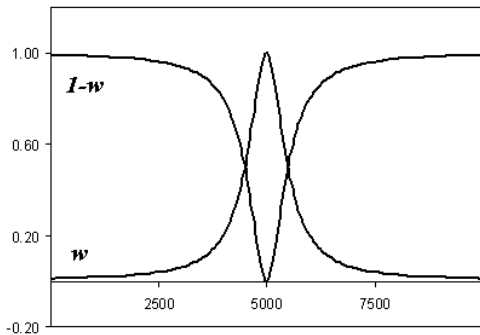
formally, with γ a scale factor,

$$w_t = \frac{1}{1 + \left(\gamma \left(\frac{Y_{t-1} - \mathcal{Y}}{\mathcal{Y}}\right)\right)^2} \quad \gamma > 0$$

WEIGHTED EXPECTATIONS

more the economy deviates from \mathcal{Y} , less weight given to extrapolative expectations

agents believe that extreme economic conditions are not sustainable



formally, with γ a scale factor,

$$w_t = \frac{1}{1 + \left(\gamma \left(\frac{Y_{t-1} - \mathcal{Y}}{\mathcal{Y}}\right)\right)^2} \quad \gamma > 0$$

COMBINED MODEL

$$Y_t = I_a + b(1 + k)E_{t-1}[Y_t] - bkE_{t-2}[Z_t]$$

$$Z_t = Y_{t-1}$$

that is

$$\begin{aligned}
 Y_t &= I_a + b(1 + k) \left[\left(\frac{1}{1 + \gamma^2 \left(\frac{Y_{t-1} - \mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Y_{t-1} + \mu_1(Y_{t-1} - \mathcal{Y})) + \right. \\
 &\quad \left. + \left(1 - \frac{1}{1 + \gamma^2 \left(\frac{Y_{t-1} - \mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Y_{t-1} + \mu_2(\mathcal{Y} - Y_{t-1})) \right] \\
 &\quad - bk \left[\left(\frac{1}{1 + \gamma^2 \left(\frac{Z_{t-1} - \mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Z_{t-1} + \mu_1(Z_{t-1} - \mathcal{Y})) + \right. \\
 &\quad \left. + \left(1 - \frac{1}{1 + \gamma^2 \left(\frac{Z_{t-1} - \mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Z_{t-1} + \mu_2(\mathcal{Y} - Z_{t-1})) \right] \\
 Z_t &= Y_{t-1}
 \end{aligned}$$

COMBINED MODEL

$$Y_t = I_a + b(1+k)E_{t-1}[Y_t] - bkE_{t-2}[Z_t]$$

$$Z_t = Y_{t-1}$$

that is

$$\begin{aligned}
 Y_t &= I_a + b(1+k) \left[\left(\frac{1}{1+\gamma^2 \left(\frac{Y_{t-1}-\mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Y_{t-1} + \mu_1(Y_{t-1} - \mathcal{Y})) + \right. \\
 &\quad \left. + \left(1 - \frac{1}{1+\gamma^2 \left(\frac{Y_{t-1}-\mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Y_{t-1} + \mu_2(\mathcal{Y} - Y_{t-1})) \right] \\
 &\quad - bk \left[\left(\frac{1}{1+\gamma^2 \left(\frac{Z_{t-1}-\mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Z_{t-1} + \mu_1(Z_{t-1} - \mathcal{Y})) + \right. \\
 &\quad \left. + \left(1 - \frac{1}{1+\gamma^2 \left(\frac{Z_{t-1}-\mathcal{Y}}{\mathcal{Y}} \right)^2} \right) (Z_{t-1} + \mu_2(\mathcal{Y} - Z_{t-1})) \right] \\
 Z_t &= Y_{t-1}
 \end{aligned}$$

JACOBIAN MATRICES

$$J(Y, Z) = \begin{pmatrix} b(1+k) \frac{dE_{t-1}[Y_t]}{dY_{t-1}} & -bk \frac{dE_{t-2}[Z_t]}{dZ_{t-1}} \\ 1 & 0 \end{pmatrix}$$

for Samuelson's equilibrium

$$J(\mathcal{Y}) = \begin{pmatrix} b(1+k)(1+\mu_1) & -bk(1+\mu_1) \\ 1 & 0 \end{pmatrix}$$

Conditions for stability of (\mathcal{Y}) (eigenvalues $|\lambda_{1,2}| < 1$)

- $1 + \text{tr } J(\mathcal{Y}) + \det J(\mathcal{Y}) > 0$ (flip at $\lambda_1 = 1$)
- $1 - \text{tr } J(\mathcal{Y}) + \det J(\mathcal{Y}) > 0$ (fold/pitchfork at $\lambda_2 = -1$)
- $1 - \det J(\mathcal{Y}) > 0$ (Neimark-Sacker at mod=1)

JACOBIAN MATRICES

$$J(Y, Z) = \begin{pmatrix} b(1+k) \frac{dE_{t-1}[Y_t]}{dY_{t-1}} & -bk \frac{dE_{t-2}[Z_t]}{dZ_{t-1}} \\ 1 & 0 \end{pmatrix}$$

for Samuelson's equilibrium

$$J(\mathcal{Y}) = \begin{pmatrix} b(1+k)(1+\mu_1) & -bk(1+\mu_1) \\ 1 & 0 \end{pmatrix}$$

Conditions for stability of (\mathcal{Y}) (eigenvalues $|\lambda_{1,2}| < 1$)

- $1 + \text{tr } J(\mathcal{Y}) + \det J(\mathcal{Y}) > 0$ (flip at $\lambda_1 = 1$)
- $1 - \text{tr } J(\mathcal{Y}) + \det J(\mathcal{Y}) > 0$ (fold/pitchfork at $\lambda_2 = -1$)
- $1 - \det J(\mathcal{Y}) > 0$ (Neimark-Sacker at mod=1)

JACOBIAN MATRICES

$$J(Y, Z) = \begin{pmatrix} b(1+k) \frac{dE_{t-1}[Y_t]}{dY_{t-1}} & -bk \frac{dE_{t-2}[Z_t]}{dZ_{t-1}} \\ 1 & 0 \end{pmatrix}$$

for Samuelson's equilibrium

$$J(\mathcal{Y}) = \begin{pmatrix} b(1+k)(1+\mu_1) & -bk(1+\mu_1) \\ 1 & 0 \end{pmatrix}$$

Conditions for stability of (\mathcal{Y}) (eigenvalues $|\lambda_{1,2}| < 1$)

- $1 + \text{tr } J(\mathcal{Y}) + \det J(\mathcal{Y}) > 0$ (flip at $\lambda_1 = 1$)
- $1 - \text{tr } J(\mathcal{Y}) + \det J(\mathcal{Y}) > 0$ (fold/pitchfork at $\lambda_2 = -1$)
- $1 - \det J(\mathcal{Y}) > 0$ (Neimark-Sacker at mod=1)

BIFURCATIONS

First always true, second and third not necessarily. Parameter assumptions: $\mu_1, k > 0$

Binding inequality:

$$\mu_1 < \frac{1-b}{b} \quad \text{if } k < 1$$

at equality a pitchfork bifurcation, \mathcal{Y} loses stability 2 new (stable) fixed points appear

$$\mu_1 < \frac{1-kb}{kb} \quad \text{if } k > 1$$

at equality a NS bifurcation, \mathcal{Y} loses stability stable invariant curves appear.

Sequences on curves represent endogenous fluctuations as a GENERIC dynamical feature.

ADDITIONAL STEADY STATES

The quadratic term in weight leads to existence of 2 steady states (\bar{Y}_1, \bar{Y}_2) symmetric about \mathcal{Y} , the solutions to

$$(\bar{Y} - \mathcal{Y})^2 = \frac{\mathcal{Y}^2 (b(1 + \mu_1) - 1)}{\gamma^2 (b(\mu_2 - 1) + 1)}.$$

- complex-valued for $\mu_1 < (1 - b)/b$
- real and equal to \mathcal{Y} at critical value pitchfork bifurcation $\mu_1 = (1 - b)/b$
- for $\mu_1 > (1 - b)/b$ real and positive

\bar{Y}_1, \bar{Y}_2 also lose stability through NS bifurcations - interesting dynamics result from relations of stable and unstable manifolds of saddle node at \mathcal{Y} and dynamics of \bar{Y}_1, \bar{Y}_2

ADDITIONAL STEADY STATES

The quadratic term in weight leads to existence of 2 steady states (\bar{Y}_1, \bar{Y}_2) symmetric about \mathcal{Y} , the solutions to

$$(\bar{Y} - \mathcal{Y})^2 = \frac{\mathcal{Y}^2 (b(1 + \mu_1) - 1)}{\gamma^2 (b(\mu_2 - 1) + 1)}.$$

- complex-valued for $\mu_1 < (1 - b)/b$
- real and equal to \mathcal{Y} at critical value pitchfork bifurcation $\mu_1 = (1 - b)/b$
- for $\mu_1 > (1 - b)/b$ real and positive

\bar{Y}_1, \bar{Y}_2 also lose stability through NS bifurcations - interesting dynamics result from relations of stable and unstable manifolds of saddle node at \mathcal{Y} and dynamics of \bar{Y}_1, \bar{Y}_2

DYNAMICS OVER PARAMETER SPACE

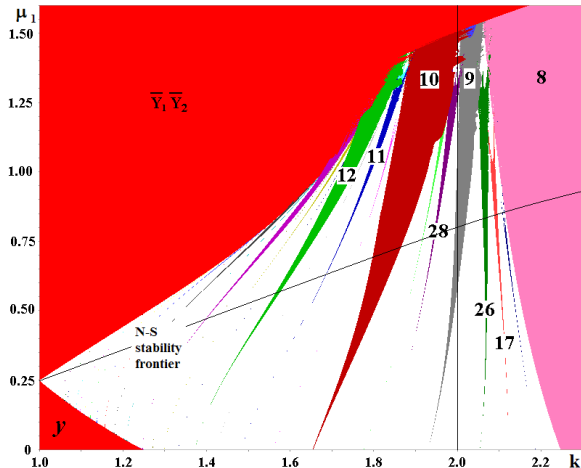
two parameter
bifurcation diagram
(k, μ_1)

fixed points - red

cycles - other colors
(periodicity)

unknown - white:
periodic (> 32),
quasiperiodic or
chaotic attractors

pitchfork $\mu_1 = 0.25$



$b = 0.8, l_a = 1000$ ($\mathcal{Y} = 5000$), $\mu_2 = 0.5, \gamma = 10, (Y_0, Z_0) = (3500, 3500)$
these and all following plots produced with `iDMC` software

BIFURCATION SCENARIO 1

$k = 2$, limit sets as μ_1 varies

\mathcal{Y} undergoes NS for $\mu_1 < 0$
(equilibrium exists but unstable)

μ_1 small - mostly quasiperiodic
attractors on invariant curves

$\mu_1 \approx 0.6$ - period-9 cycles

$\mu_1 \approx 1.15$ - chaotic and periodic
windows alternate

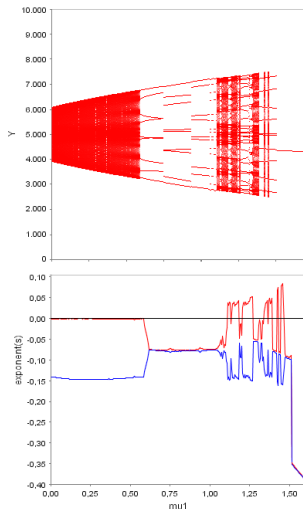
$\mu_1 > 1.5$ - fixed point $\bar{Y}_1 < \mathcal{Y}$

Lyapunov exponents - time ave
divergence nearby trajectories

2 negative - periodic cycle;

1 negative 1 zero - quasiperiodic;

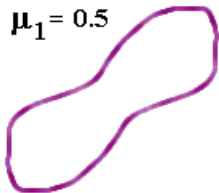
1 negative 1 positive - chaotic.



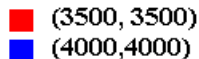
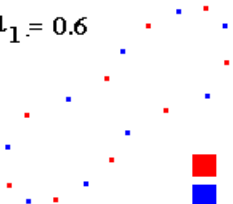
FROM QUASI TO PERIODIC DYNAMICS

from both initial conditions convergence to invariant circle

$$\mu_1 = 0.5$$



$$\mu_1 = 0.6$$



from each initial condition convergence to a different period-9 cycle

k AS BIFURCATION PARAMETER

setting

$$\mu_1 = 0.6$$

$$1 < k < 2.3$$

for all

$$\mu_1 > 0.25 \mathcal{Y}$$

is unstable

as k

increases:

fixed points,

quasi and

periodic

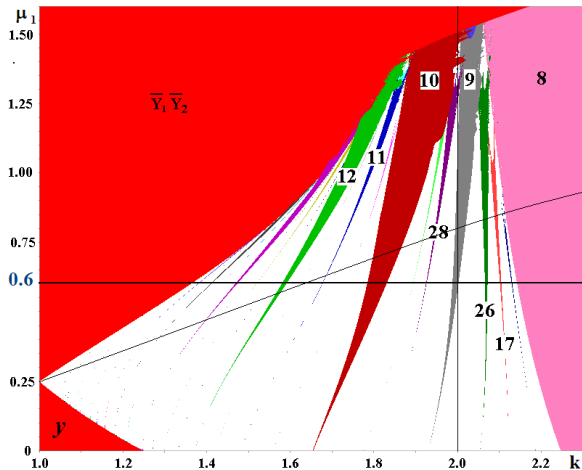
attractors,

period-8 cycle

with

multi-stability

at transition



BIFURCATION SCENARIO 2

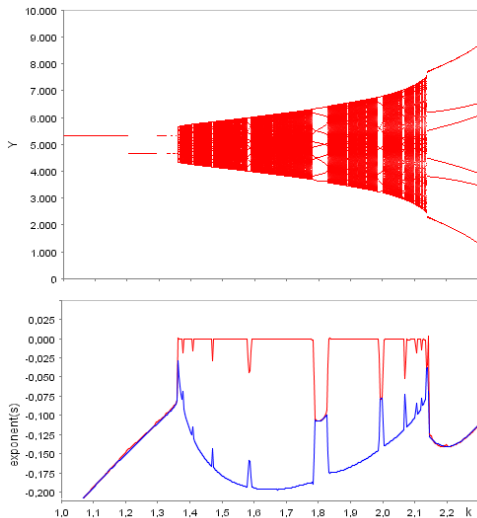
from (4000,4000)

for small k ($\mu_1 = 0.6$) \mathcal{Y}
unstable

$\bar{Y}_1 = 4658$, $\bar{Y}_2 = 5342$
stable with respective
basins which become
more entwined as k
increased

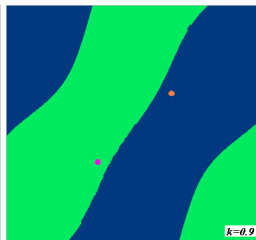
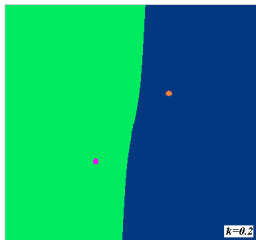
larger fluctuations
alternating on invariant
curve between quasi
and periodic attractors

period-8 cycle (outside
invariant curve) first
stable then loses
stability



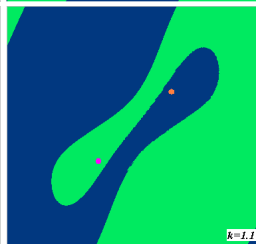
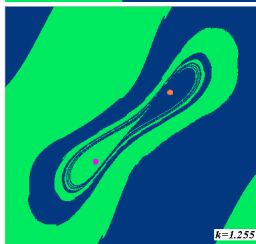
STEADY STATE BASINS ENTWINE

distinct
basins for
 \bar{Y}_1, \bar{Y}_2 ,
separated
by stable
manifold \mathcal{Y}



eigenvalues
complex,
basins
begin to
distort

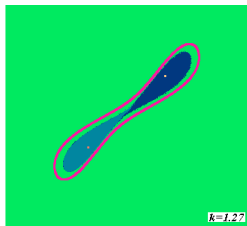
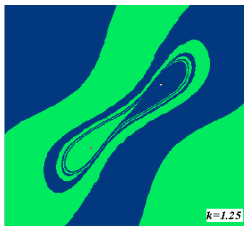
dense con-
volutions
form ring



convolutions
around 3
fixed points

FROM FOCI TO INVARIANT CURVE

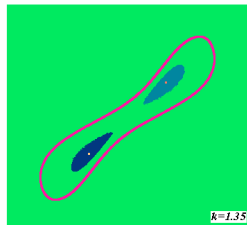
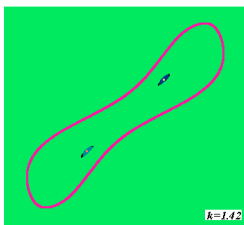
dense con-
volutions
near where
attracting
curve, Γ_s
will appear



enclosed is
repelling
 Γ_u , forming
a separatrix

homoclinic
connection

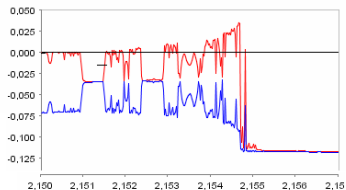
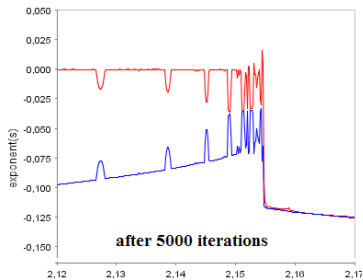
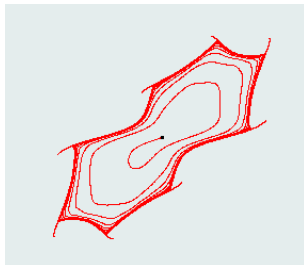
foci lose
stability
through
Neimark-
Sacker
bifurcation

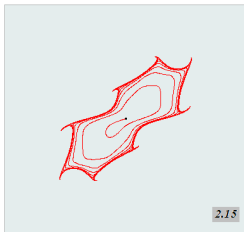
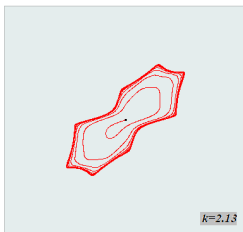
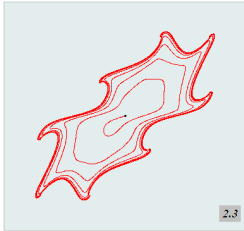
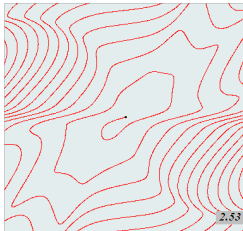


double
homoclinic
loop, basins
disjoint

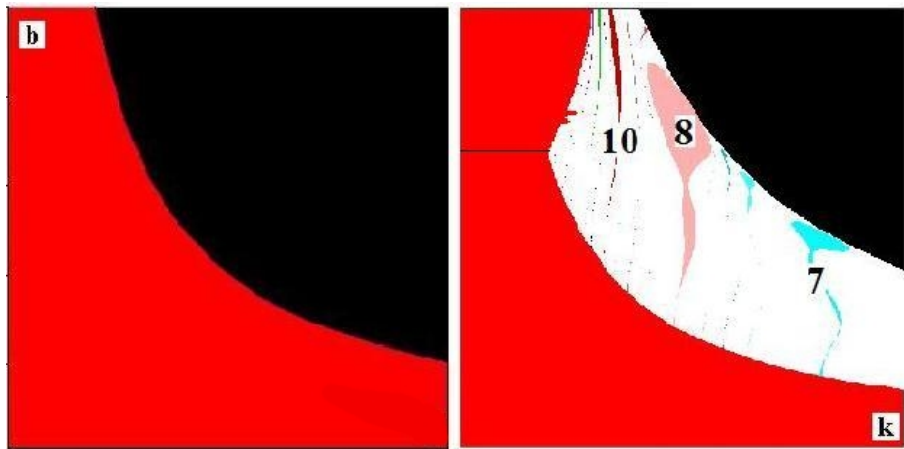
CHAOTIC TRANSITIONS

transversal crossing of loop sequence associated with chaotic repeller and long chaotic transients - below unstable manifold from Samuelson equilibrium near transition at $k = 2.155$ leads to chaotic frills at boundary of invariant curve and period-8 cycle



UNSTABLE MANIFOLDS OF γ invariant
curveclose to
chaotic
attractorperiod-8
cycle loses
stability, no
attractorsunstable
manifold
converges
to period-8
cycle

COMPARISON OF LIMIT SETS IN ORIGINAL PARAMETER SPACE



$\mu_1 = \mu_2 = 0.5$, $l_a = 1000$, $\gamma = 10$, $(Y_0, Z_0) = (4000, 4000)$, $\infty = 10^{10}$, transients are 5000, max period 32, precision 0.01

SAMUELSON'S MULTIPLIER-ACCELERATOR WITH HETEROGENEOUS EXPECTATIONS

- conditions for **local stability** of Samuelson's equilibrium are more restrictive
- but **global stability** continues as trajectories converge to
 - either of two co-existing stable steady states
 - closed curves with periodic or quasiperiodic sequences
 - chaotic attractors
- more of the original parameter space (k, b) leads to **persistent oscillations**

SAMUELSON'S MULTIPLIER-ACCELERATOR WITH HETEROGENEOUS EXPECTATIONS

- conditions for **local stability** of Samuelson's equilibrium are more restrictive
- but **global stability** continues as trajectories converge to
 - either of two co-existing stable steady states
 - closed curves with periodic or quasiperiodic sequences
 - chaotic attractors
- more of the original parameter space (k, b) leads to **persistent oscillations**

SAMUELSON'S MULTIPLIER-ACCELERATOR WITH HETEROGENEOUS EXPECTATIONS

- conditions for **local stability** of Samuelson's equilibrium are more restrictive
- but **global stability** continues as trajectories converge to
 - either of two co-existing stable steady states
 - closed curves with periodic or quasiperiodic sequences
 - chaotic attractors
- more of the original parameter space (k, b) leads to **persistent oscillations**

LOCAL vs. GLOBAL DYNAMICS

GENERAL ISSUES in DYNAMICAL ANALYSIS

economic models are nonlinear and the study of **linearized versions around a steady state** is only the beginning of dynamical analysis

which, given

- widespread availability of cheap, powerful computers
- open-source software
- developments in dynamical systems theory

should be accompanied by **the analysis of global dynamics**

- with more attention to quasiperiodic and chaotic limit sets especially in **business cycle theory**
- and to the effects of disturbance processes on dynamics by studying models as **stochastic processes**

LOCAL vs. GLOBAL DYNAMICS

GENERAL ISSUES in DYNAMICAL ANALYSIS

economic models are nonlinear and the study of **linearized versions around a steady state** is only the beginning of dynamical analysis

which, given

- widespread availability of cheap, powerful computers
- open-source software
- developments in dynamical systems theory

should be accompanied by **the analysis of global dynamics**

- with more attention to quasiperiodic and chaotic limit sets especially in **business cycle theory**
- and to the effects of disturbance processes on dynamics by studying models as **stochastic processes**

LOCAL vs. GLOBAL DYNAMICS

GENERAL ISSUES in DYNAMICAL ANALYSIS

economic models are nonlinear and the study of **linearized versions around a steady state** is only the beginning of dynamical analysis

which, given

- widespread availability of cheap, powerful computers
- open-source software
- developments in dynamical systems theory

should be accompanied by **the analysis of global dynamics**

- with more attention to quasiperiodic and chaotic limit sets especially in **business cycle theory**
- and to the effects of disturbance processes on dynamics by studying models as **stochastic processes**

REFERENCES

Lines, M., Westerhoff, F., 2006. Expectations and the multiplier-accelerator model, in: Puu, T., Sushko, I. (Eds.), *Business Cycle Dynamics. Models and Tools*, Springer-Verlag, Berlin, pp. 255-276.

Lines, M., 2007a. Bifurcation scenarios in a heterogeneous agent, multiplier-accelerator model. *Pure Mathematics and Applications* 16, 429-442

see these for more references on heterogeneous expectations, multi-stability and global dynamics

WORKSHOP

INTERACTING AGENTS AND NONLINEAR DYNAMICS IN MACROECONOMICS

UDINE, ITALY JUNE 9-11 2010

Invited speakers

Carl Chiarella, Rainer Franke, Paul de Grauwe, Cars Hommes, Tom Lux, Jan Tunistra

Open Sessions are being organized by Sebastiano Manzan